The new IRB 580

Top model functions - compact design





**ABB** Automation

## PRECISION

ABB Flexible Automation proudly presents IRB 580, an exciting addition to our line of high precision paint robots.

### Precision - our commitment to quality

Precision has always been our primary goal and the common denominator of our globally renowned paint robots. IRB 580 takes precision painting a step further by combining the advanced functions of the IRB 5400 series with a compact design. The result is a highly flexible, cost-effective and accurate paint robot system, which compliments our 540 and 5400 series with the same relentless commitment to quality that our customers have relied on since 1969.

#### Why choose IRB 580 over its competitors

- \* High precision and efficiency ABB's Paint Saving Technology, low overspray, reduced cycle time.
- \* Increased flexibility two different arm lengths and ABB's patented Hollow Wrist Technology.
- \* Energy saving fully balanced construction, low power consumption, 30-50% less than our competitors.
- \* Increased productivity quicker installation and online software editing, ABB's Superior Control Technology.

#### 140° unsurpassed flexibility

The ABB Hollow Wrist can rotate 140° in any direction. This unsurpassed flexibility makes IRB 580 one of the most versatile and easy to program paint robots in its class.

#### Straight wrist, no off-set

The main feature of robot arms with ABB's Hollow Wrist Technology is that all paint- and air supply hoses are encapsulated in the arm and wrist. This prevents damage to the hoses, and the straight design eliminates wear and tear thus increasing overall reliability.

#### **High precision**

The Hollow Wrist is built around three wedgeshaped rotating links, controlled by three axis motors, enclosed in the rear end of the horizontal arm. This design combined with our advanced software solutions gives greater accuracy and payload capability.

With 140° rotation in any direction IRB 580 will fully coat even the most complicated parts

#### 2

The straight design of the wrist increases durability.

#### 3+4

The ABB Hollow Wrist can be fitted with a number of different applicators, including bells and various guns.

#### **ABB's Hollow Wrist Technology:**

## The highly accurate Hollow Wrist









#### **ABB's Paint Saving Technology:**

# IPS - the intelligent paint solution

#### **Fast and accurate**

ABB's unique Integrated Process System features closed loop regulation and highspeed control for paint and airflow adjustment. The system ensures a uniform film build with a specified thickness over the entire object. This assures a high finish quality and optimum use of paint material.

#### Significant paint savings

The IPS system increases transfer efficiency by synchronising the gun needle and paint flow triggering with the robot arm motion, keeping overspray to an absolute minimum. This saves paint and increases your costeffectiveness.

#### Increased uptime

The IPS system will automatically compensate for physical changes in the environment or the equipment, always keeping the commanded flow rate within strict tolerances. The system will monitor all the set limits and warn the operator of any equipment wear over time. It can also detect a broken cable or defective sensor and automatically enter open loop operation mode, if so configured. The system can operate in this mode until it is convenient to enter the booth and perform the necessary maintenance. This will drastically increase uptime in case of sensor or cable failure.



Accurate paint flow triggering saves paint. An adjustment of

points of a program will typical

ly save you 14 litres per day \*)

\*) (@ 1000 mm/sec, 1000 ml/min,

45 racks/hour, 4 parts/rack, 2

2 cm for the gun triggering

for one robot only.

shifts)





Triggering is typically better than +/- 2ms. This shows the accurate repeatability of the IPS with 12 gun «on» and «off». Built in know-how. The IPS software is integrated in the robot arm.



IRB 580 - paint robot by design. By integrating the paint process equipment in the robot arm, we have significantly increased the process response time and have reduced paint and solvent waste.



#### **ABB's Superior Control Technology:**

### Increased productivity and cost-effectiveness

#### Superior reliability and safety

The S4P controller is modular and designed to the highest level of operational reliability. The twin channel safety system is continuously monitored and complies fully with international safety standards. The balanced arm, which has brakes on all axes, improves ease of use and personnel safety.

#### Substantial energy savings

Energy consumption is 50 - 70% that of other robot systems, and is achieved by well-balanced robot arms and an optimised drive-train design. Motors and drives are the same modern types as in our top-line IRB 5400 robots giving high speed and precision.

#### Increased productivity

With powerful PC software tools like CAP and FlexUI you can optimise your paint programs without interrupting production. This will ensure a continuously improved finish quality, optimised use of paint material and increased production uptime.

#### **Flexible connectivity**

Using standard, popular industrial communication protocols, IRB 580 communicates easily with your factory network, PLC's and line controllers. This capability allows you to monitor and control your paint cell and to collect production data and paint statistics.

#### **Faster installation**

IRB 580 comes pre-configured, ready to install with its integrated paint process equipment and interface for PLC's. Just start adding the robot paint commands in the powerful RAPID programming language and you're quickly up and running. Powerful PC software tools allow process tuning without interrupting production.

#### 3

Because of the S4P, ABB's Global Controller Platform, training, service and engineering costs can be significantly reduced.

#### 2+4

IRB 580 is available with two different arm lengths, 1220 mm and 1620 mm.





ABB	-	
-4		











#### IRB 580 **TECHNICAL DATA**

#### **SPECIFICATION IRB 580**

Handling capacity	10Kg		
Number of axes	6		
Diskette drive	3.5" MS-DOS format		
Axis movements			
Axis	Working range	Max. speed	
1. Rotation	300°	112°/sec	
2. Vertical arm	145°	112°/sec	
3. Horizontal arm	95°	112°/sec	
4. Inner wrist	≈indefinite	415°/sec	
5. Wrist bend	≈indefinite	400°/sec	
6. Outer wrist	920°	560°/sec	
Pose accuracy	0,3mm		
Path accuracy	+/- 3mm		

#### **ELECTRICAL CONNECTION**

Supply voltage	3phase 200V-600V 5	0/60Hz
Power consumption	Max. peek effect	4.5KVA
Power consumption during production		<700W
Power consumption «stand by»		<0.3KVA

#### Electrical safety according to international standards

#### PHYSICAL

			D
Dimensions			Baseware US
Robot footprint	600m	nm x 700mm	
Robot main axes	Base 630mm (Hig	h), Ø800mm	RAPID
	Vertical arm	1000mm	Conveyor tracki
	Horizontal arm	1220mm	
		1620mm	
Cabinet	Height	1280mm	
	Width	800mm	
	Depth	850mm	PROCESSV
Weight	Robot unit 1220mm	657Kg	APR
	Robot unit 1620mm	660Kg	
	Robot controller	240Kg	IPS

#### ENVIRONMENT

North America	Class 1, Div. 1, Group	C&D		architecture philoso
Japan Europe	IIGT4 (pending)		PC TOOLS	
Luiope	1014		CAP for S4P	A bundle containing
EMC	Electro Magnetic Com	Electro Magnetic Compatibility certi-		Editor and RobView
	ficate		ShopFloor Editor	Off-line editing of pr
Ambient temperature	Robot unit	5-45°C		graphics for path an
	Robot controller	5-52°C	RobView	Monitoring of robots
Relative humidity	Max. 95% Non conde	Max. 95% Non condensing		production. Easy de
			RobLog	Logging of robot and
Degree of protection	Robot unit	IP 67		into a standard PC o
	Robot controller	IP 54		trending and analysi



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#### ABB Flexible Automation AS

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#### USER INTERFACES Operator panel

Operator panel Programming unit	In cabinet or external Exi protected. Portable, joystick and keyboard
	Display 16lines x 40 characters
	Graphical 240 x 320 pixels
	Distributed intelligence
Safaty	EMV stop, Enable device, Conoral
Odlety	mode stop. Auto mode stop. Test mode
	stop, Cabin interlock
MACHINE INTER	FACES
Digital input/output	512/512
Analogue inputs/outputs	16/12
Remote I/O	Interbus-S 64/64
	Allen Bradley RIO 128/128
	Profibus DP 128/128
	CC-Link 128/128
Serial channels	RS-232, RS-422, RS-485
Network	Ethernet NFS/FTP
	RAP Robot Application protocol
	FactoryWare interface
BASEWARE	
BaseWare OS	Robot Operating System, multitasking capability
RAPID	Powerful application programming language
Conveyor tracking	Accurate synchronisation of robotic motion, paint process regulation and the moving
	ors in any direction
PROCESSWARE	
APR	Analogue Paint Regulation of process para-
	meters as fluid, air and electrostatic voltage
IPS	Integrated Process System. Unique system
	for closed loop regulation and high-speed
	control for paint and airflow adjustments.
	Based on an open, flexible and adjustable architecture philosophy
PC TOOLS	

4P	A bundle containing the ShopFloor
	Editor and RobView
<sup>-</sup> Editor	Off-line editing of programs using 3D
	graphics for path and process adjustments
	Monitoring of robots and process in
	production. Easy design of user screens
	Logging of robot and process data
	into a standard PC database-file for
	trending and analysis